

Introduction

Overview of the Class

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Information Technology Center

Technical & Scientific Computing II (4820-1028)
Seminar on Computer Science II (4810-1205)
Parallel FEM

- Target: Parallel FEM
- Supercomputers and Computational Science
- Overview of the Class
- Future Issues

Technical & Scientific Computing II

Seminar on Computer Science II

科学技術計算II・コンピュータ科学特別講義II

- Parallel FEM
 - **Introduction to Parallel Programming by MPI**
 - Data Structure for Parallel FEM
 - How to develop parallel codes
 - Exercise on Oakleaf-FX (Fujitsu PRIMEHPC FX10)
 - Parallel version of “fem3d” (3D static linear-elastic FEM code) in Summer Semester
 - Technical & Scientific Computing I, Seminar on Computer Science I

Motivation for Parallel Computing

(and this class)

- Large-scale parallel computer enables fast computing in large-scale scientific simulations with detailed models. Computational science develops new frontiers of science and engineering.
- Why parallel computing ?
 - faster & larger
 - “larger” is more important from the view point of “new frontiers of science & engineering”, but “faster” is also important.
 - + more complicated
 - Ideal: Scalable
 - Solving N^x scale problem using N^x computational resources during same computation time.

Scientific Computing = SMASH

Science

Modeling

Algorithm

Software

Hardware

- You have to learn many things.
- Collaboration (or Co-Design) will be important for future career of each of you, as a scientist and/or an engineer.
 - You have to communicate with people with different backgrounds.
 - It is more difficult than communicating with foreign scientists from same area.

This Class ...

Science

- Parallel FEM using MPI

Modeling

- Science: 3D Solid Mechanics

Algorithm

- Modeling: FEM

- Algorithm: Iterative Solvers etc.

Software

Hardware

- You have to know many components to learn FEM, although you have already learned each of these in undergraduate and high-school classes.

Road to Programming for “Parallel” Scientific Computing

Programming for Parallel Scientific Computing
(e.g. Parallel FEM/FDM)

Programming for Real World Scientific Computing
(e.g. FEM, FDM)

Big gap here !!

Programming for Fundamental Numerical Analysis
(e.g. Gauss-Seidel, RK etc.)

Unix, Fortran, C etc.

The third step is important !

- How to parallelize applications ?
 - How to extract parallelism ?
 - If you understand methods, algorithms, and implementations of the original code, it's easy.
 - “Data-structure” is important

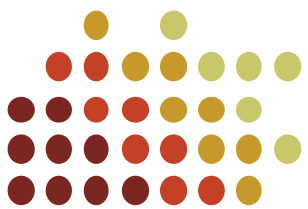
4. Programming for Parallel Scientific Computing
(e.g. Parallel FEM/FDM)

3. Programming for Real World Scientific Computing
(e.g. FEM, FDM)

2. Programming for Fundamental Numerical Analysis
(e.g. Gauss-Seidel, RK etc.)

1. Unix, Fortran, C etc.

- How to understand the code ?
 - Reading the application code !!
 - It seems primitive, but very effective.
 - In this class, “reading the source code” is encouraged.
 - 3: Summer, 4: Fall/Winter Semesters

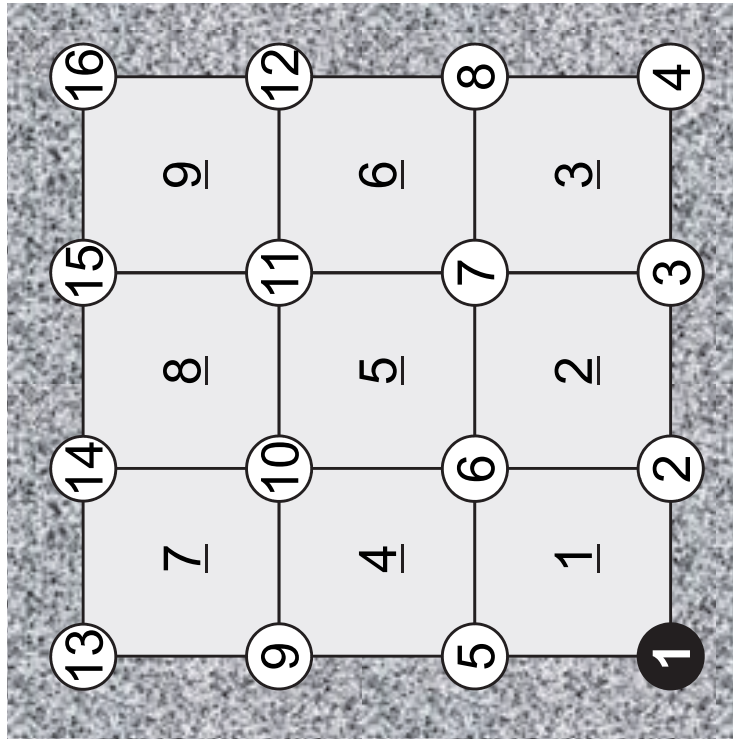


Finite-Element Method (FEM)

- One of the most popular numerical methods for solving PDE's.
- elements (meshes) & nodes (vertices)
- Consider the following 2D heat transfer problem:

$$\lambda \left(\frac{\partial^2 T}{\partial x^2} + \frac{\partial^2 T}{\partial y^2} \right) + Q = 0$$

- 16 nodes, 9 bi-linear elements
- uniform thermal conductivity ($\lambda=1$)
- uniform volume heat flux ($Q=1$)
- $T=0$ at node 1
- **Insulated boundaries**





Galerkin FEM procedures

- Apply Galerkin procedures to each element:

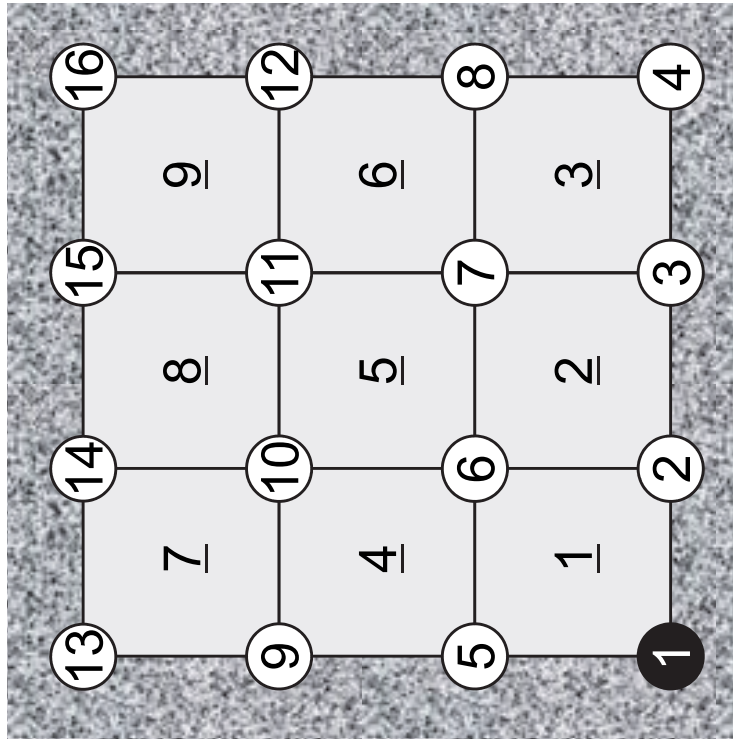
where $T = [N]\{\phi\}$ in each elem.

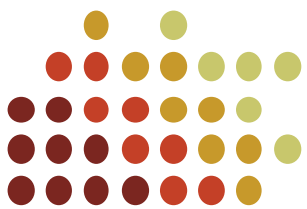
$$\int_V [N]^T \left\{ \lambda \left(\frac{\partial^2 T}{\partial x^2} + \frac{\partial^2 T}{\partial y^2} \right) + Q \right\} dV = 0$$

$\{\phi\}$: T at each vertex
 $[N]$: Shape function
 (Interpolation function)

- Introduce the following “weak form” of original PDE using Green’s theorem:

$$-\int_V \lambda \left(\frac{\partial [N]^T}{\partial x} \frac{\partial [N]}{\partial x} + \frac{\partial [N]^T}{\partial y} \frac{\partial [N]}{\partial y} \right) dV \cdot \{\phi\} + \int_V Q [N]^T dV = 0$$

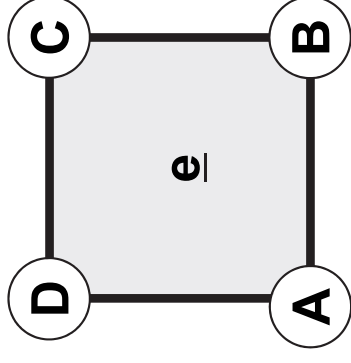




Element Matrix

- Apply the integration to each element and form “element” matrix.

$$-\int_V \lambda \left(\frac{\partial [N]^T}{\partial x} \frac{\partial [N]}{\partial x} + \frac{\partial [N]^T}{\partial y} \frac{\partial [N]}{\partial y} \right) dV \cdot \{\phi\} + \int_V Q [N]^T dV = 0$$



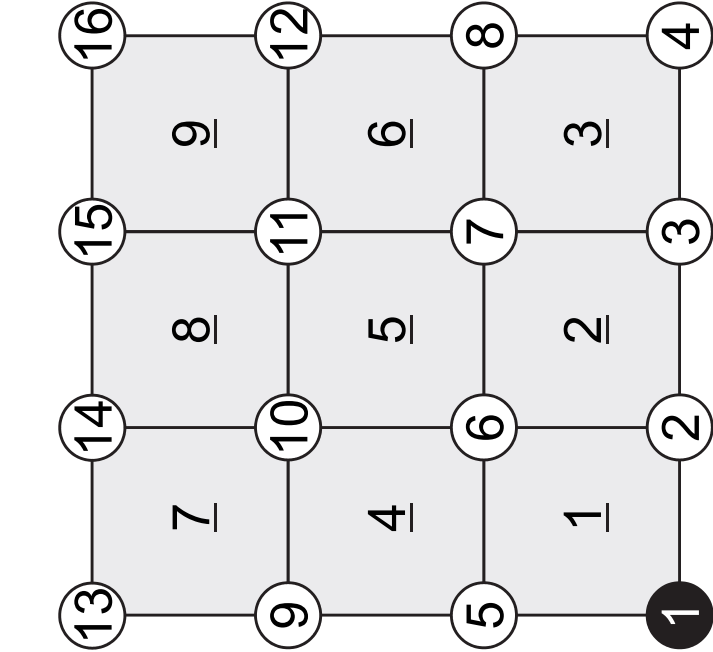
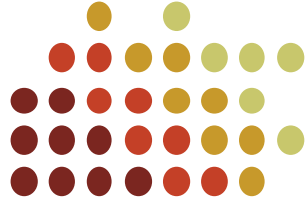
$$[k^{(e)}] \{\phi^{(e)}\} = \{f^{(e)}\}$$

$$\begin{bmatrix} k_{AA}^{(e)} & k_{AB}^{(e)} & k_{AC}^{(e)} & k_{AD}^{(e)} \\ k_{BA}^{(e)} & k_{BB}^{(e)} & k_{BC}^{(e)} & k_{BD}^{(e)} \\ k_{CA}^{(e)} & k_{CB}^{(e)} & k_{CC}^{(e)} & k_{CD}^{(e)} \\ k_{DA}^{(e)} & k_{DB}^{(e)} & k_{DC}^{(e)} & k_{DD}^{(e)} \end{bmatrix} \begin{Bmatrix} \phi_A^{(e)} \\ \phi_B^{(e)} \\ \phi_C^{(e)} \\ \phi_D^{(e)} \end{Bmatrix} = \begin{Bmatrix} f_A^{(e)} \\ f_B^{(e)} \\ f_C^{(e)} \\ f_D^{(e)} \end{Bmatrix}$$



Global (Overall) Matrix

Accumulate each element matrix to “global” matrix.



$$[K] \{\Phi\} = \{F\}$$

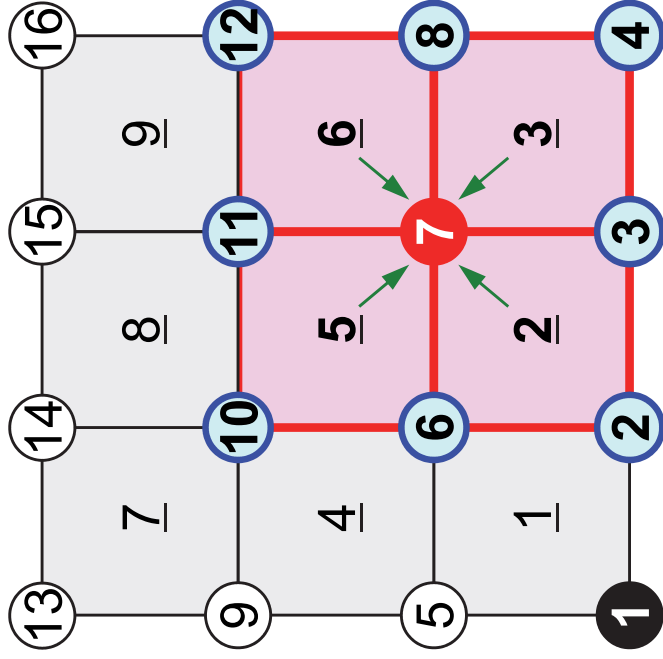
D	X							X	X								
X	D	X						X	X	X							
	X	D	X					X	X	X	X						
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X	X			D	X			D	X				X	X			
X	X	X		X	D	X		X	X	X	X		X	X	X		
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$$\left[\begin{array}{c} \Phi_1 \\ \Phi_2 \\ \Phi_3 \\ \Phi_4 \\ \Phi_5 \\ \Phi_6 \\ \Phi_7 \\ \Phi_8 \\ \Phi_9 \\ \Phi_{10} \\ \Phi_{11} \\ \Phi_{12} \\ \Phi_{13} \\ \Phi_{14} \\ \Phi_{15} \\ \Phi_{16} \end{array} \right] = \left[\begin{array}{c} F_1 \\ F_2 \\ F_3 \\ F_4 \\ F_5 \\ F_6 \\ F_7 \\ F_8 \\ F_9 \\ F_{10} \\ F_{11} \\ F_{12} \\ F_{13} \\ F_{14} \\ F_{15} \\ F_{16} \end{array} \right]$$

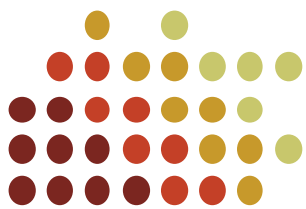
To each node ...

Effect of surrounding elem's/nodes are accumulated.

$[K]\{\Phi\} = \{F\}$



$$\begin{bmatrix}
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 \end{bmatrix}
 =
 \begin{bmatrix}
 F_1 \\ F_2 \\ F_3 \\ F_4 \\ F_5 \\ F_6 \\ F_7 \\ F_8 \\ F_9 \\ F_{10} \\ F_{11} \\ F_{12} \\ F_{13} \\ F_{14} \\ F_{15} \\ F_{16}
 \end{bmatrix}$$

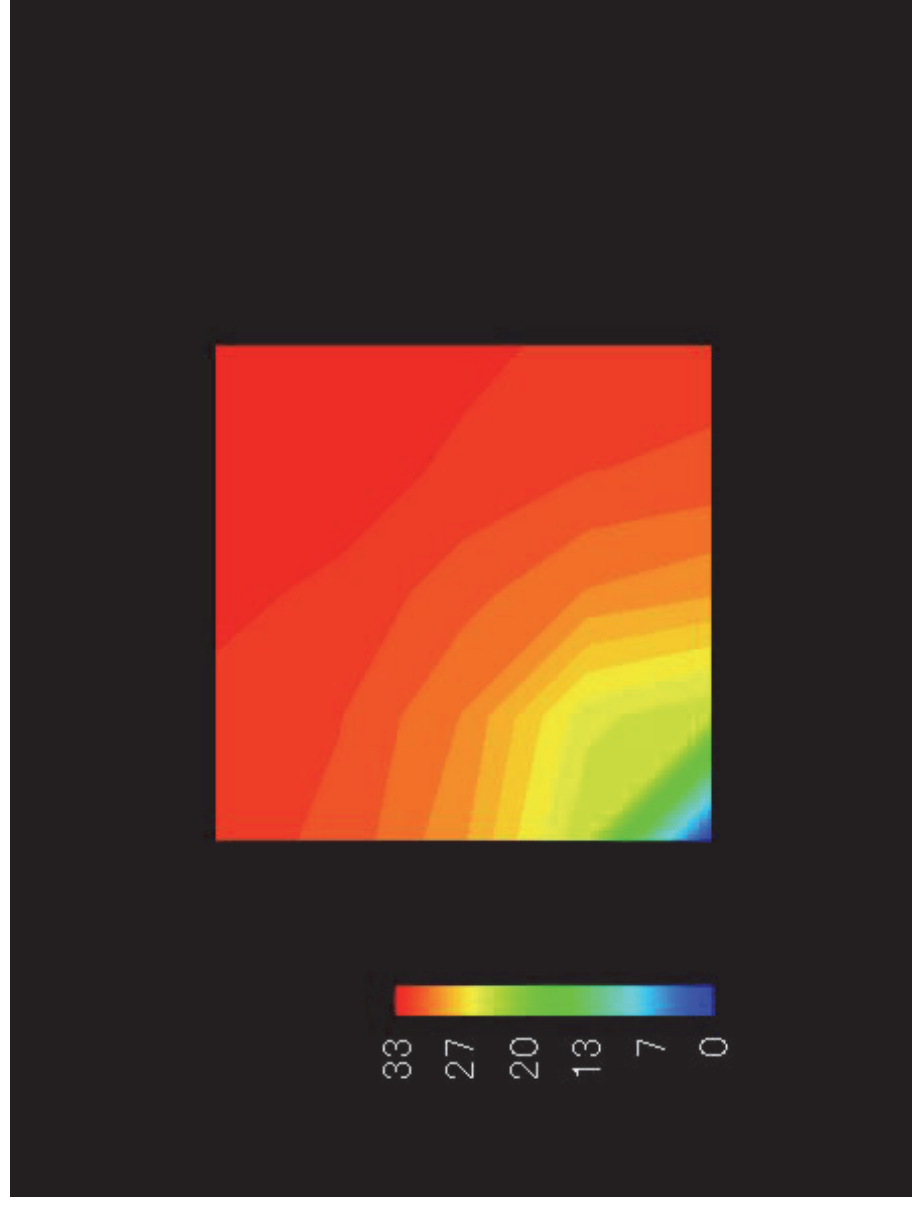


Solve the obtained global eqn's

under certain boundary conditions
($\Phi_1=0$ in this case)

$$\begin{bmatrix}
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 X & D & X & & X & X & X & & & & & & & & & & \\
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 \end{bmatrix}
 \begin{bmatrix}
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 \end{bmatrix}
 =
 \begin{bmatrix}
 F_1 \\ F_2 \\ F_3 \\ F_4 \\ F_5 \\ F_6 \\ F_7 \\ F_8 \\ F_9 \\ F_{10} \\ F_{11} \\ F_{12} \\ F_{13} \\ F_{14} \\ F_{15} \\ F_{16}
 \end{bmatrix}$$

Result ...



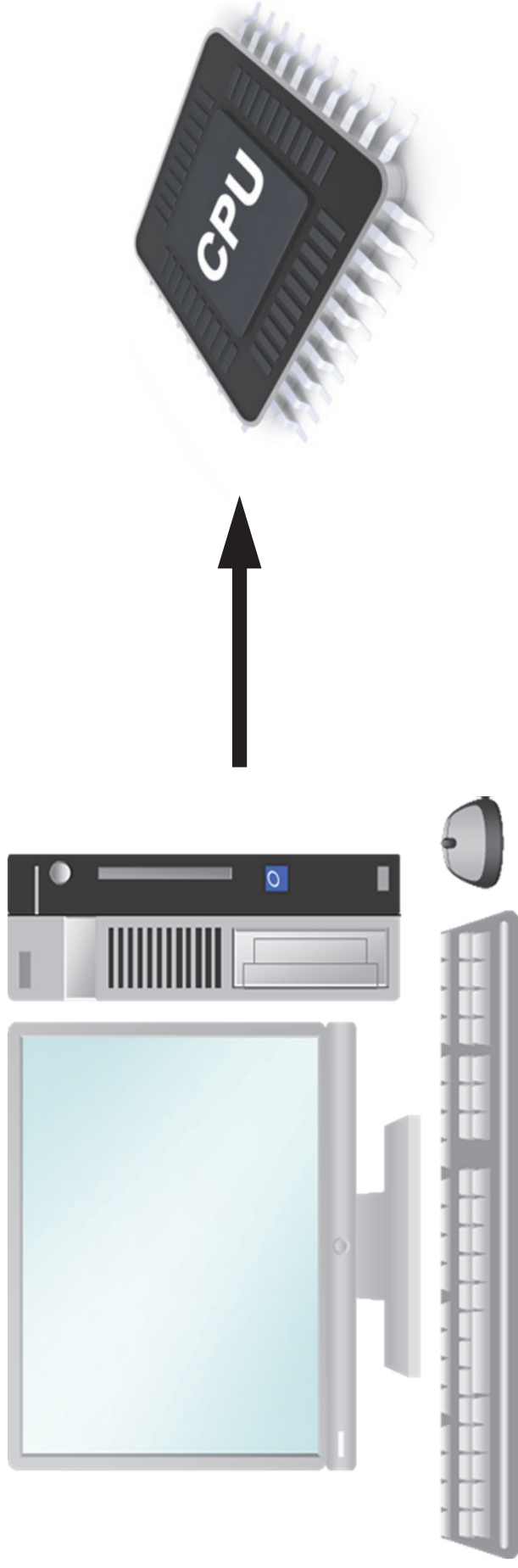


Features of FEM applications

- Typical Procedures for FEM Computations
 - Input/Output
 - Matrix Assembling
 - Linear Solvers for Large-scale Sparse Matrices
 - Most of the computation time is spent for matrix assembling/formation and solving linear equations.
- **HUGE** “indirect” accesses
 - memory intensive
- Local “element-by-element” operations
 - sparse coefficient matrices
 - suitable for parallel computing
- Excellent modularity of each procedure

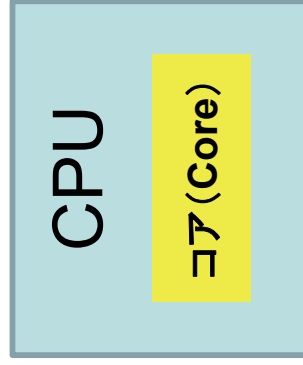
- Target: Parallel FEM
- **Supercomputers and Computational Science**
- Overview of the Class
- Future Issues

Computer & CPU

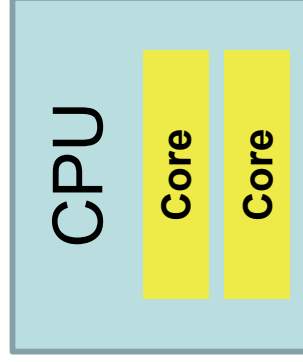


- Central Processing Unit (中央处理装置) : CPU
- CPU's used in PC and Supercomputers are based on same architecture
- GHz: Clock Rate
 - Frequency: Number of operations by CPU per second
 - GHz -> 10^9 operations/sec
 - Simultaneous 4-8 instructions per clock

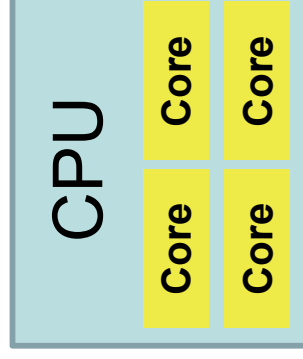
Multicore CPU



Single Core
1 cores/CPU

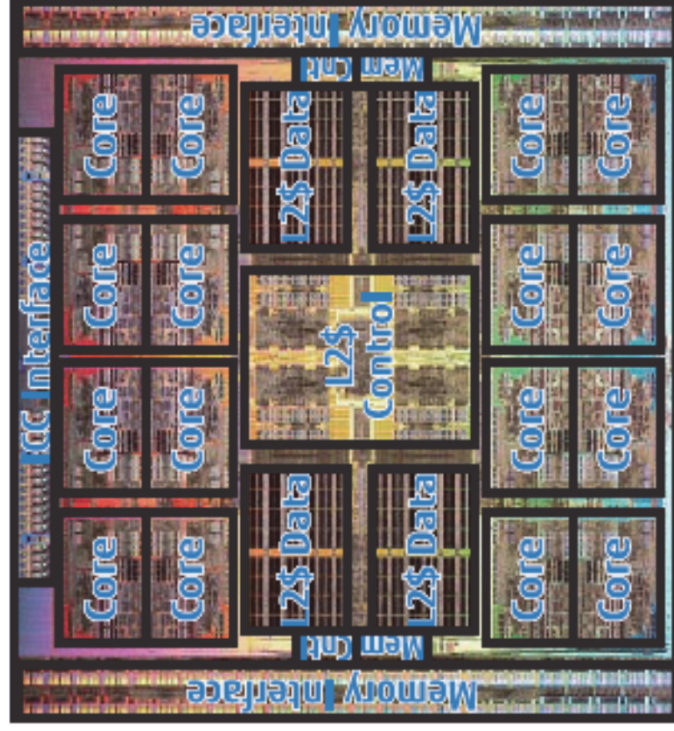


Dual Core
2 cores/CPU



Quad Core
4 cores/CPU

- Core= Central part of CPU
- Multicore CPU's with 4-8 cores are popular



- GPU: Manycore
 - $O(10^1)$ - $O(10^2)$ cores
- More and more cores
 - Parallel computing
- Oakleaf-FX at University of Tokyo: 16 cores
 - SPARC64™ IXfx

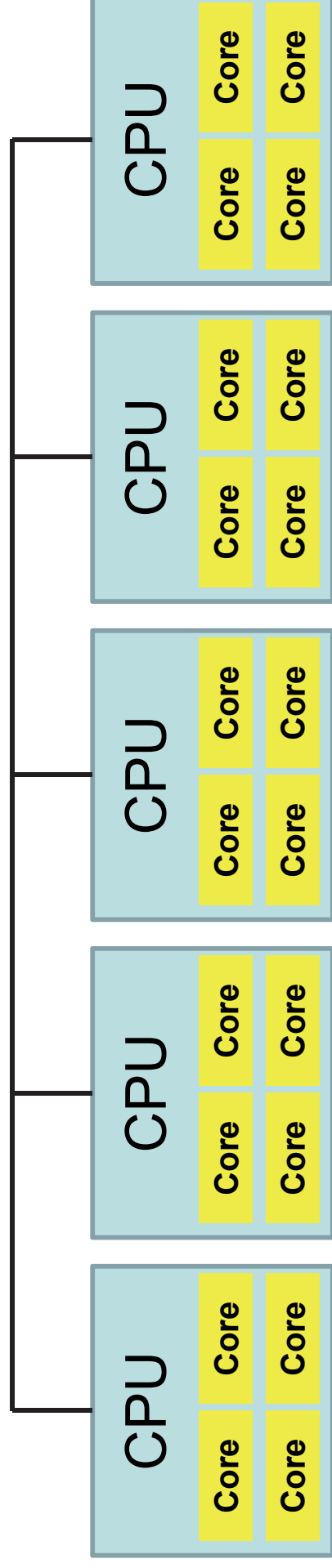
GPU/Manycores

- GPU: Graphic Processing Unit
 - GPGPU: General Purpose GPU
 - $O(10^2)$ cores
 - High Memory Bandwidth
 - Cheap
 - NO stand-alone operations
 - Host CPU needed
 - Programming: CUDA, OpenACC
- Intel Xeon/Phi: Manycore CPU
 - 60 cores
 - High Memory Bandwidth
 - Unix, Fortran, C compiler
 - Currently, host CPU needed
 - Stand-alone will be possible soon

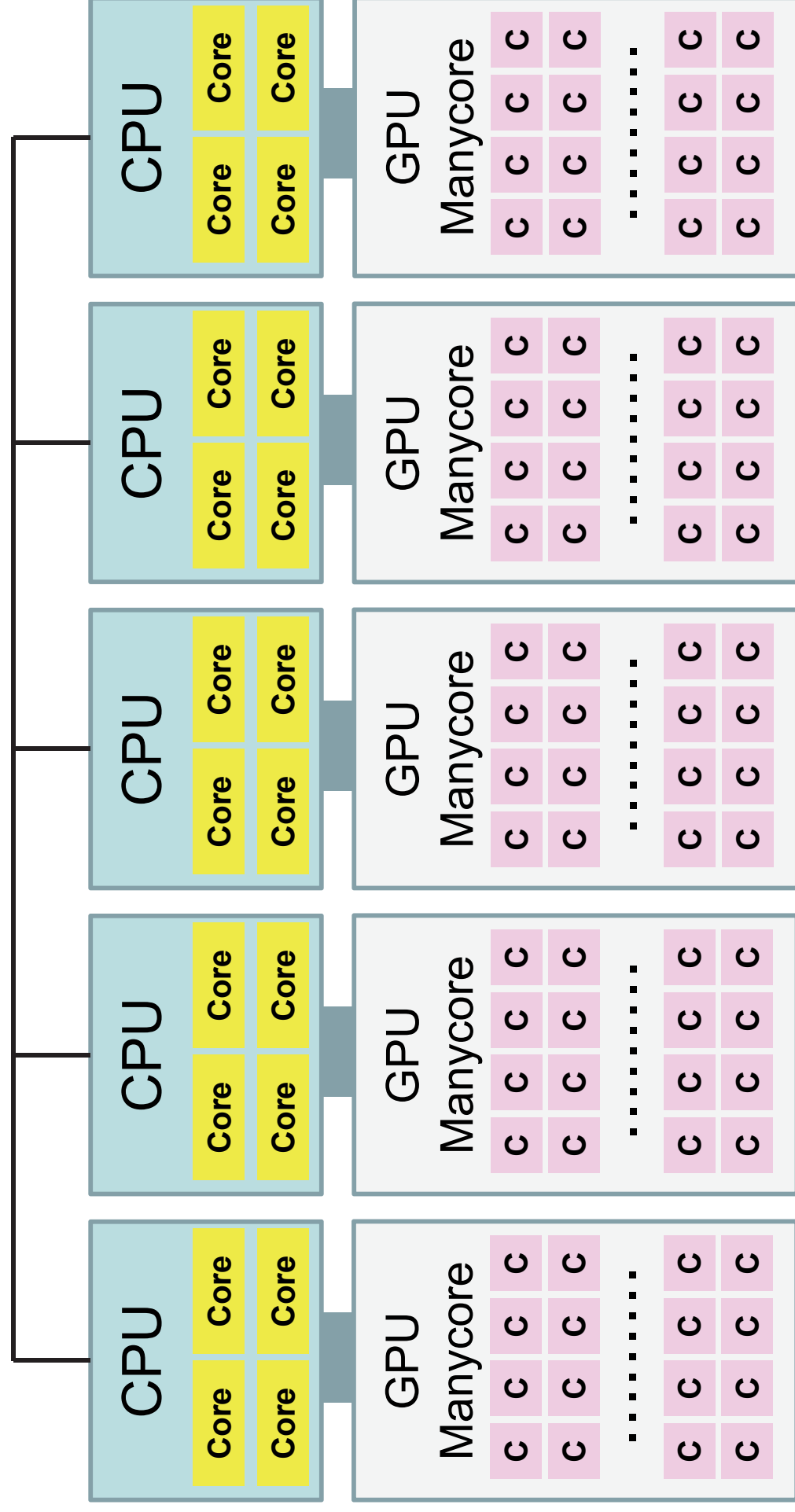


Parallel Supercomputers

Multicore CPU's are connected through network



Supercomputers with Heterogeneous/Hybrid Nodes

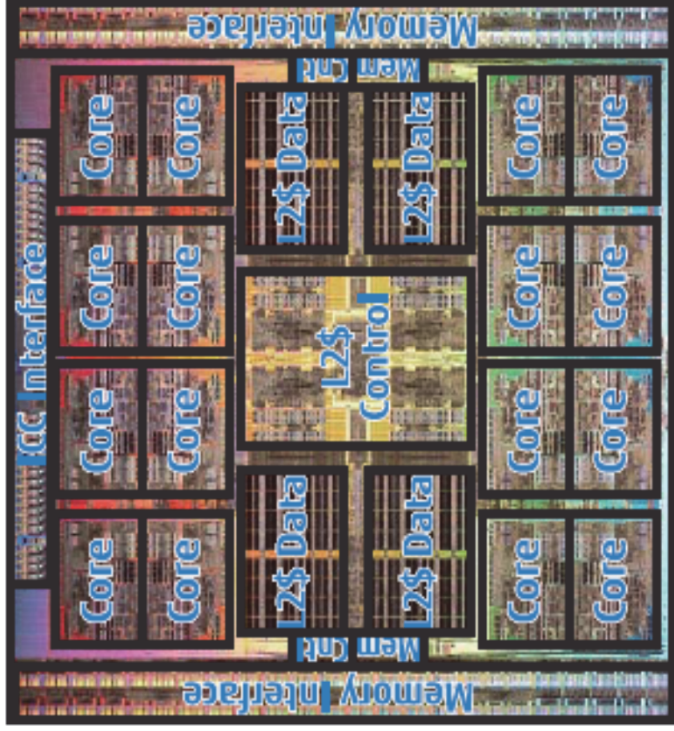


Performance of Supercomputers

- Performance of CPU: Clock Rate
- FLOPS (Floating Point Operations per Second)
 - Real Number
- Recent Multicore CPU
 - 4-8 FLOPS per Clock
 - (e.g.) Peak performance of a core with 3GHz
 - $3 \times 10^9 \times 4(\text{or } 8) = 12(\text{or } 24) \times 10^9 \text{ FLOPS} = 12(\text{or } 24) \text{ GFLOPS}$
- $10^6 \text{ FLOPS} = 1 \text{ Mega FLOPS} = 1 \text{ MFLOPS}$
 - $10^9 \text{ FLOPS} = 1 \text{ Giga FLOPS} = 1 \text{ GFLOPS}$
 - $10^{12} \text{ FLOPS} = 1 \text{ Tera FLOPS} = 1 \text{ TFLOPS}$
 - $10^{15} \text{ FLOPS} = 1 \text{ Peta FLOPS} = 1 \text{ PFLOPS}$
 - $10^{18} \text{ FLOPS} = 1 \text{ Exa FLOPS} = 1 \text{ EFLOPS}$

Peak Performance of Oakleaf-FX

Fujitsu PRIMEHPC FX10 at U.Tokyo



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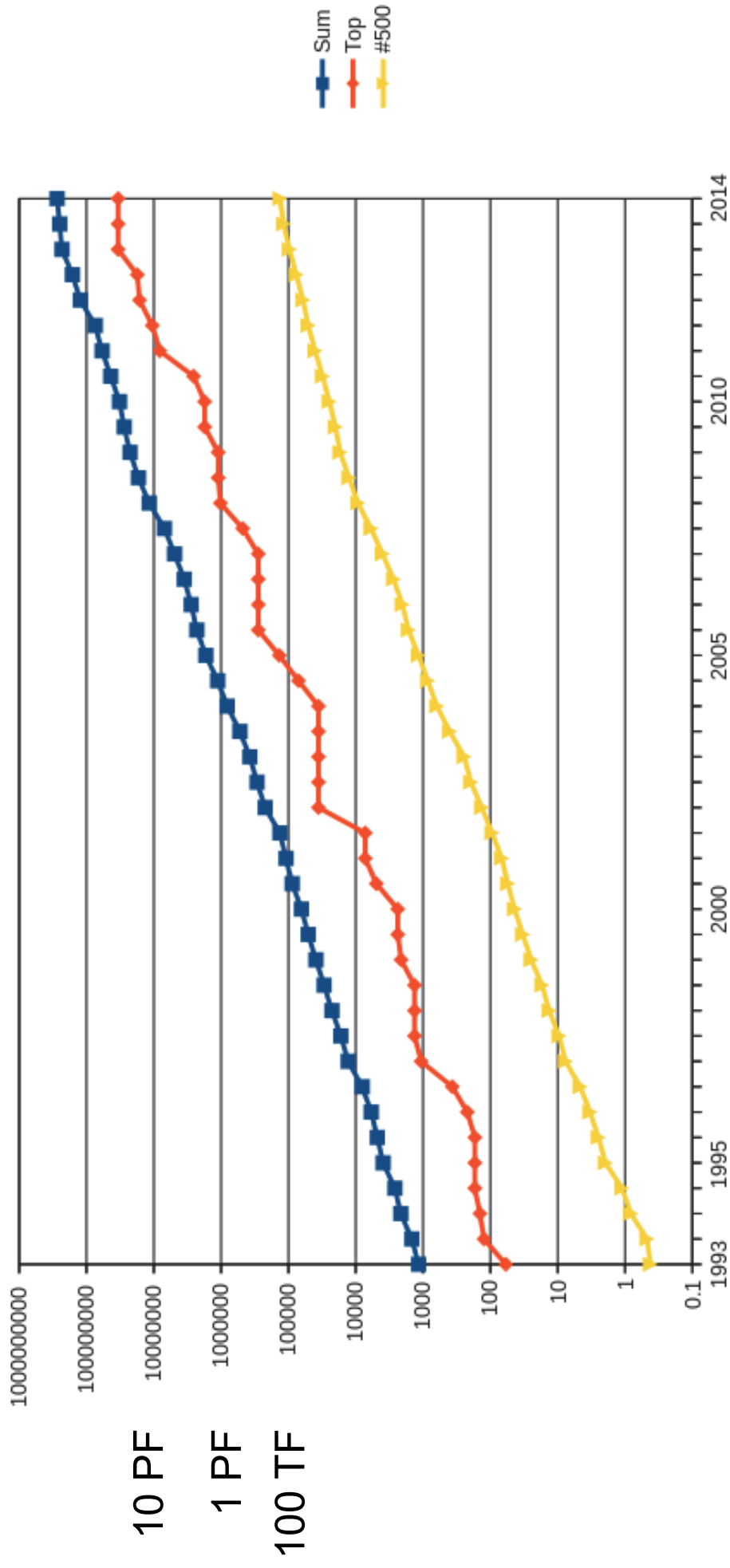
- 1.848 GHz
- 8 FLOP operations per Clock
- Peak Performance (1 core)
 - $1.848 \times 8 = 14.78$ GFLOPS
- Peak Performance (1 node/16 cores)
 - 236.5 GFLOPS
- Peak Performance of Entire Performance
 - 4,800 nodes, 76,800 cores
 - 1.13 PFLOPS

TOP 500 List

<http://www.top500.org/>

- Ranking list of supercomputers in the world
- Performance (FLOPS rate) is measured by “Linpack” which solves large-scale linear equations.
 - Since 1993
 - Updated twice a year (International Conferences in June and November)
- Linpack
 - iPhone version is available

GFLOPS



- PFLOPS: Peta ($=10^{15}$) Floating Operations per Sec.
- Exa-FLOPS ($=10^{18}$) will be attained in 2020

43rd TOP500 List (June, 2014)

	Site	Computer/Year	Vendor	Cores	R _{max}	R _{peak}	Power
1	National Supercomputing Center in Tianjin, China	Tianhe-2 Intel Xeon E5-2692, TH Express-2, IXeon Phi2013 NUDT		3120000	33863 (= 33.9 PF)	54902	17808
2	Oak Ridge National Laboratory, USA	Titan Cray XK7/NVIDIA K20x, 2012 Cray		560640	17590	27113	8209
3	Lawrence Livermore National Laboratory, USA	Sequoia BlueGene/Q, 2011 IBM		1572864	17173	20133	7890
4	RIKEN AICS, Japan	K computer, SPARC64 VIIIfx , 2011 Fujitsu		705024	10510	11280	12660
5	Argonne National Laboratory, USA	Mira BlueGene/Q, 2012 IBM		786432	8587	10066	3945
6	Swiss Natl. Supercomputer Center, Switzerland	Piz Daint Cray XC30/NVIDIA K20x, 2013, Cray		115984	6271	7789	2325
7	TACC, USA	Stampede Xeon E5-2680/Xeon Phi, 2012 Dell		462462	5168	8520	4510
8	Forschungszentrum Juelich (FZJ), Germany	JuQUEEN BlueGene/Q, 2012 IBM		458752	5009	5872	2301
9	DOE/NNSA/LLNL, USA	Vulcan BlueGene/Q, 2012 IBM		393216	4293	5033	1972
10	Government, USA	Cray XC30, 2013 Cray		225984	3144	4881	-

R_{max}: Performance of Linpack (TFLOPS)

R_{peak}: Peak Performance (TFLOPS), Power: kW

43rd TOP500 List (June, 2014)

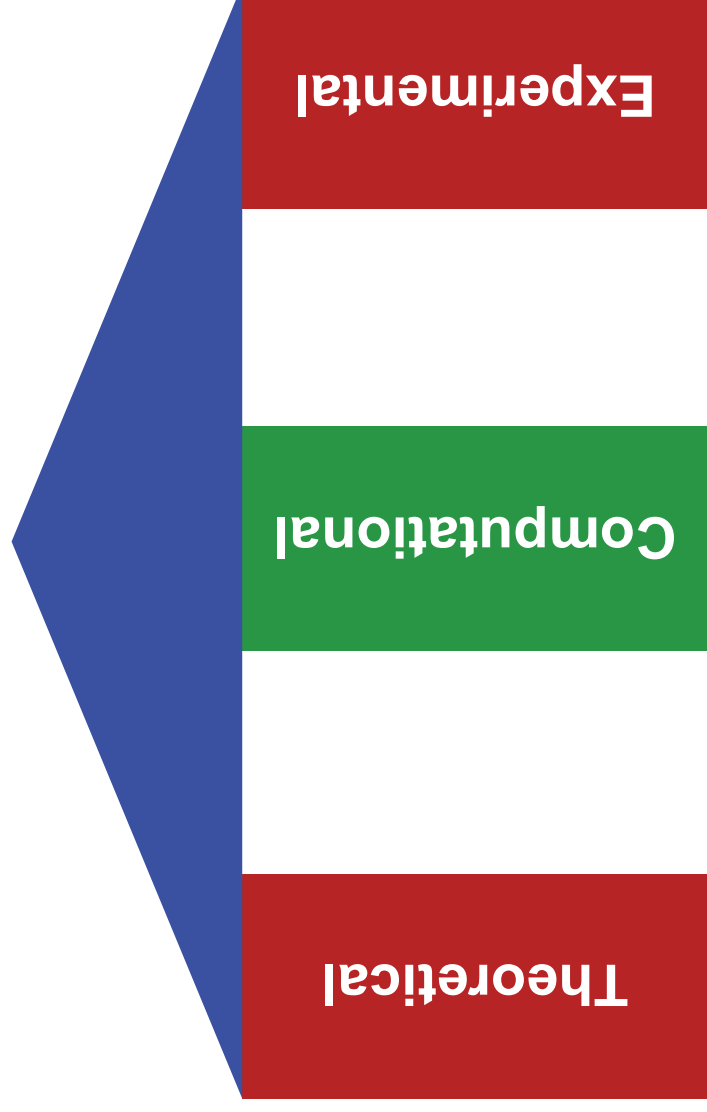
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10	Government, USA	Cray XC30, 2013 Cray		225984	3144	4881	-
36	ITC/U. Tokyo Japan	Oakleaf-FX SPARC64 IXfx, 2012 Fujitsu		76800	1043	1135	1177

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Computational Science

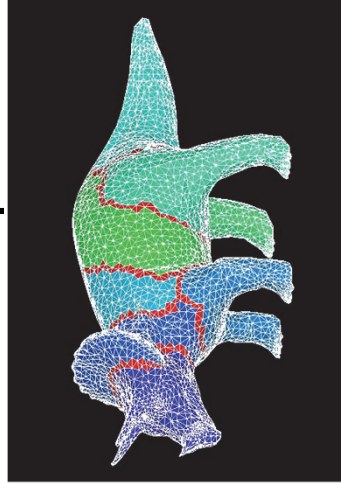
The 3rd Pillar of Science

- Theoretical & Experimental Science
- Computational Science
 - The 3rd Pillar of Science
 - Simulations using Supercomputers

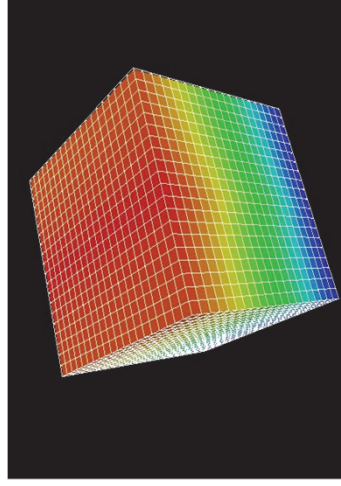


Methods for Scientific Computing

- Numerical solutions of PDE (Partial Diff. Equations)
- Grids, Meshes, Particles
 - Large-Scale Linear Equations
 - Finer meshes provide more accurate solutions



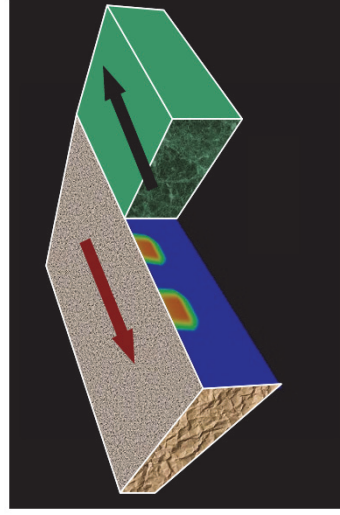
有限要素法
Finite Element Method
FEM



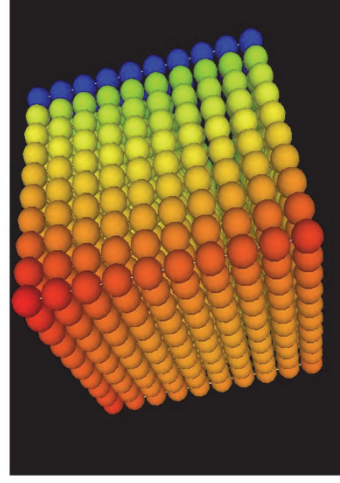
差分法
Finite Difference Method
FDM



有限体積法
Finite Volume Method
FVM



境界要素法
Boundary Element Method
BEM

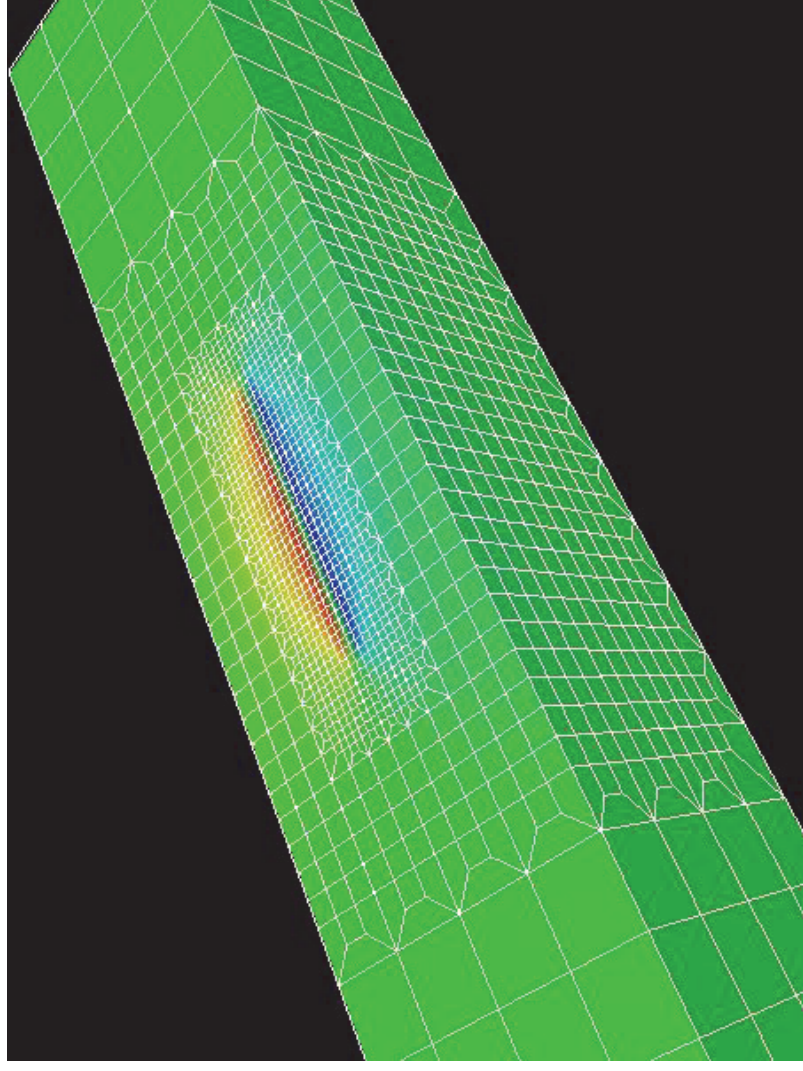
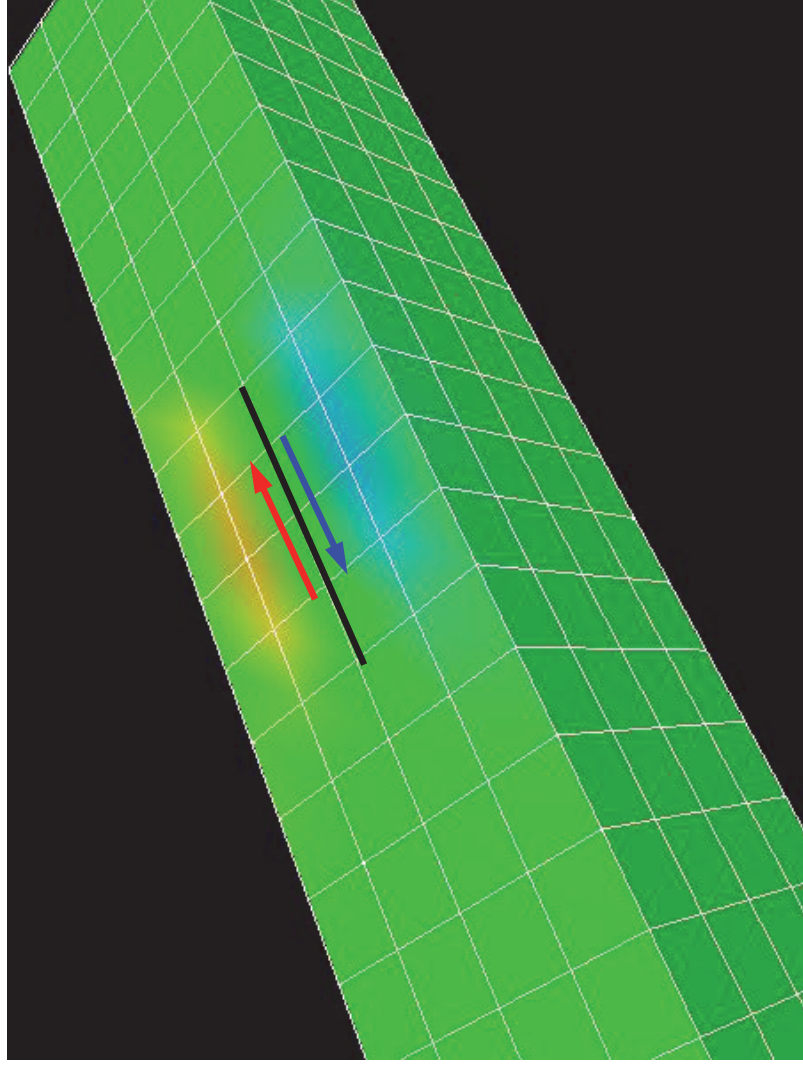


個別要素法
Discrete Element Method
DEM

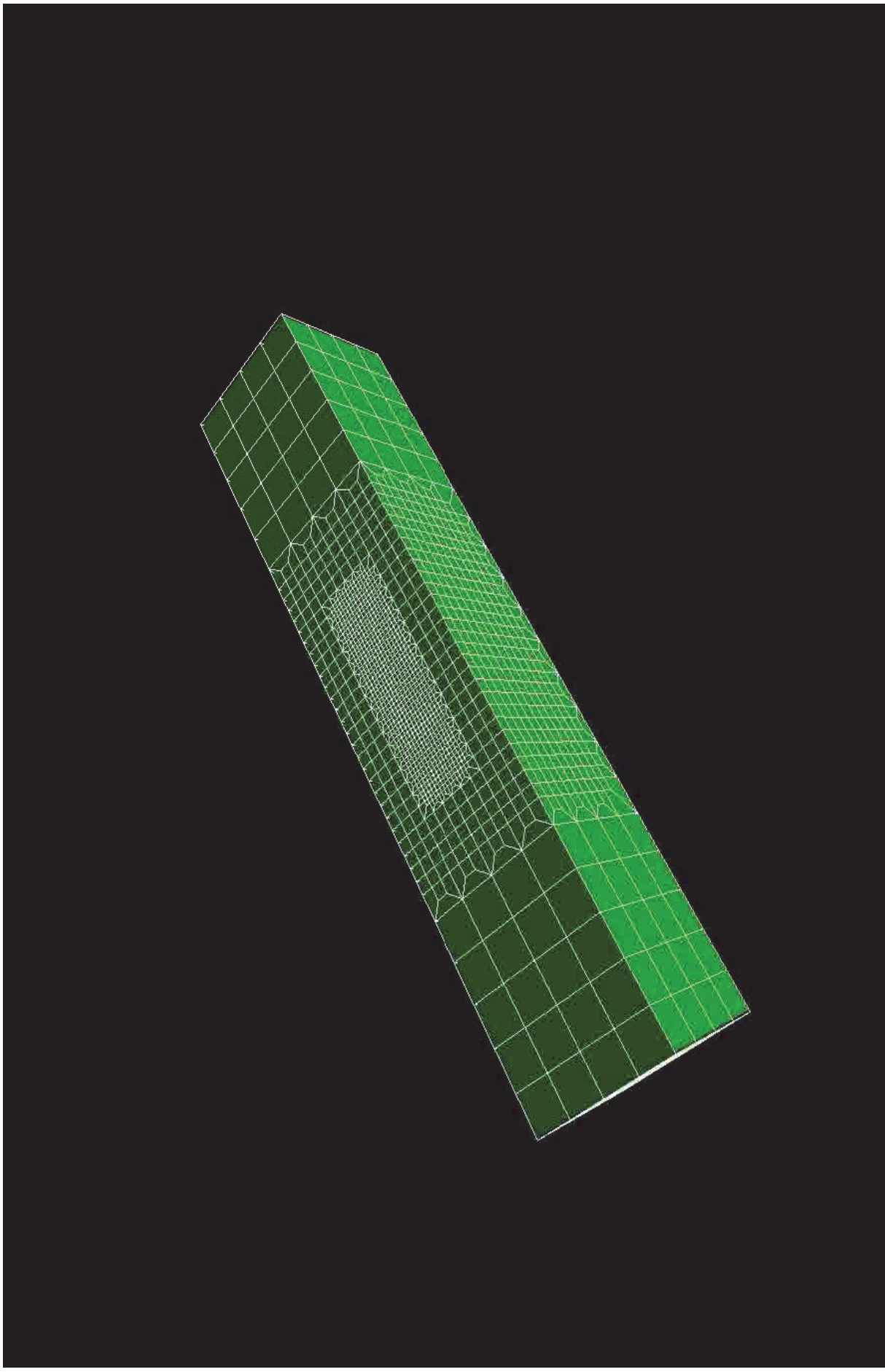
3D Simulations for Earthquake Generation Cycle

San Andreas Faults, CA, USA

Stress Accumulation at Transcurrent Plate Boundaries

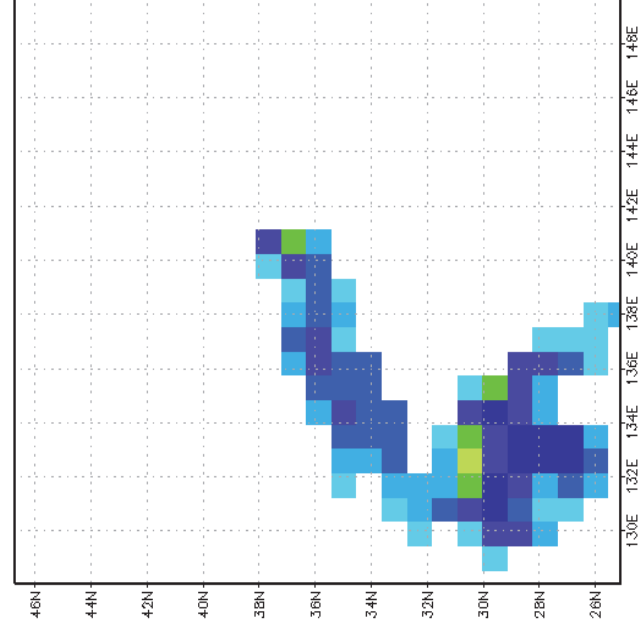


Adaptive FEM: High-resolution needed at meshes with large deformation (large accumulation)

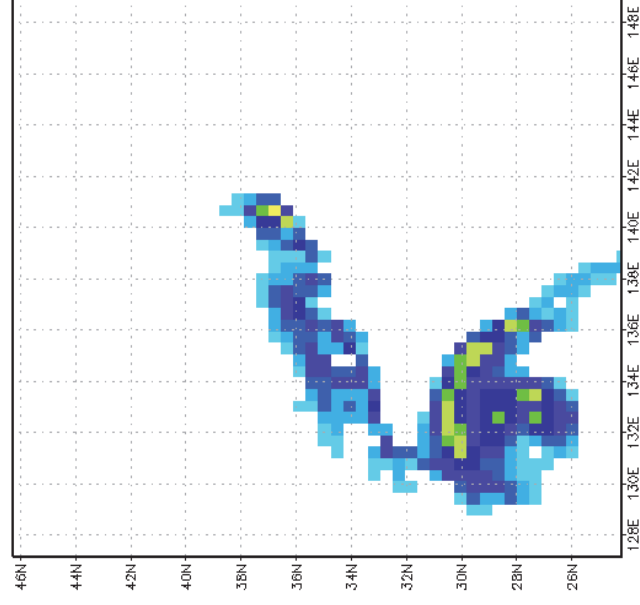


Typhoon Simulations by FDM

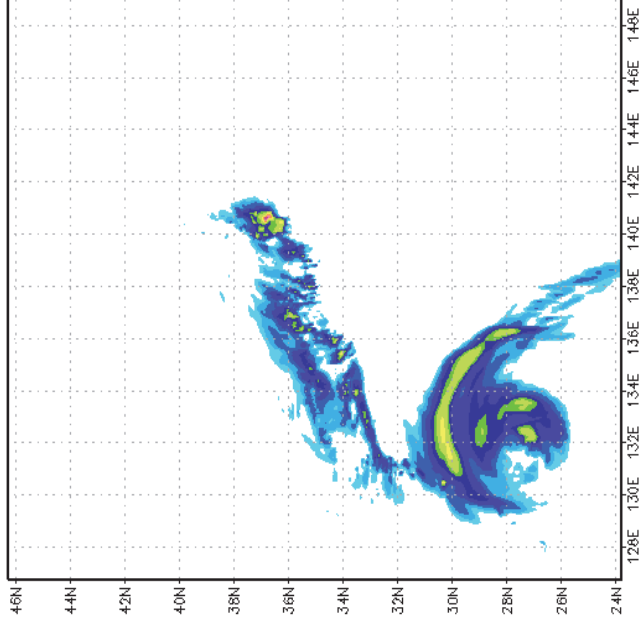
Effect of Resolution



$\Delta h = 100\text{km}$

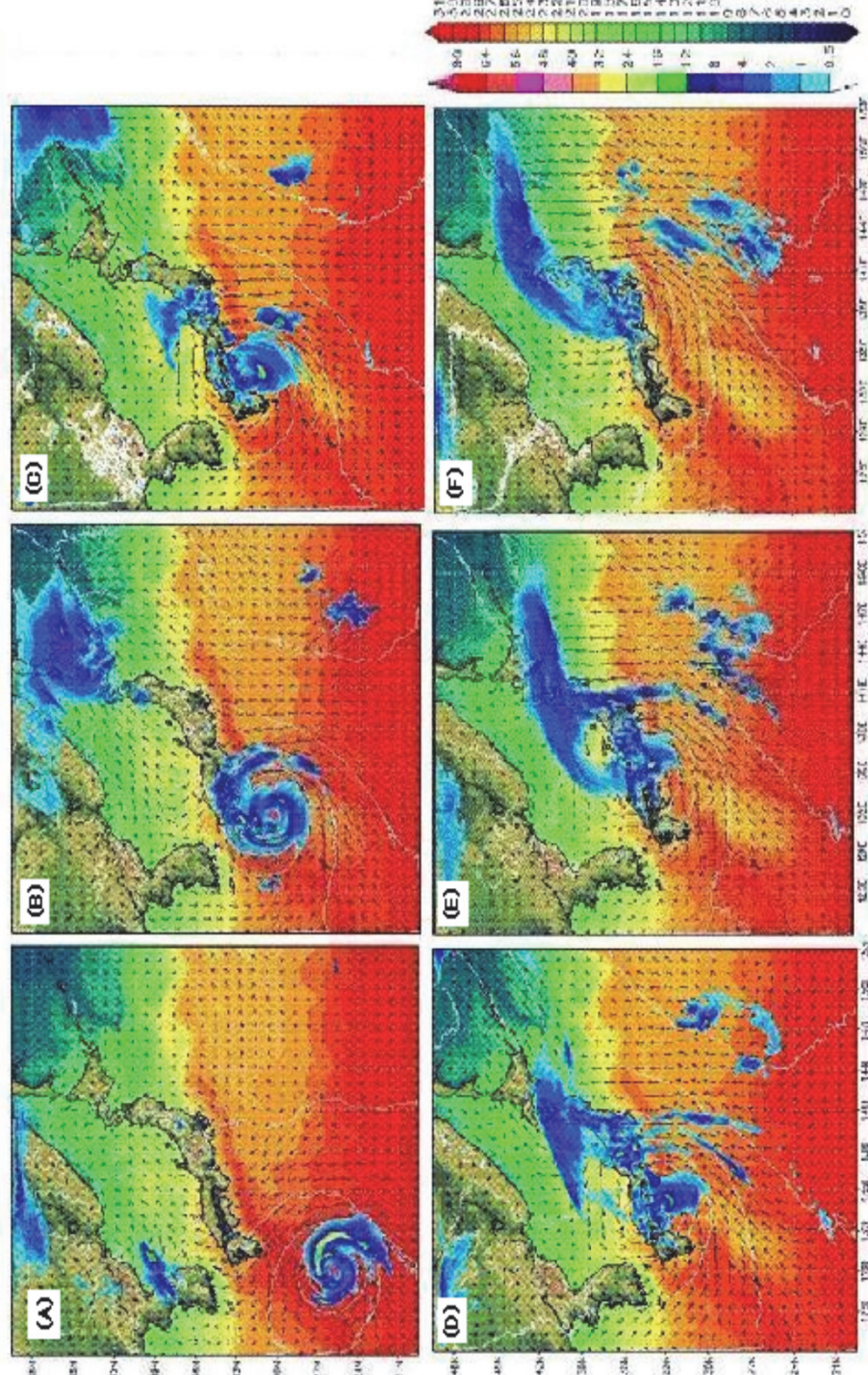
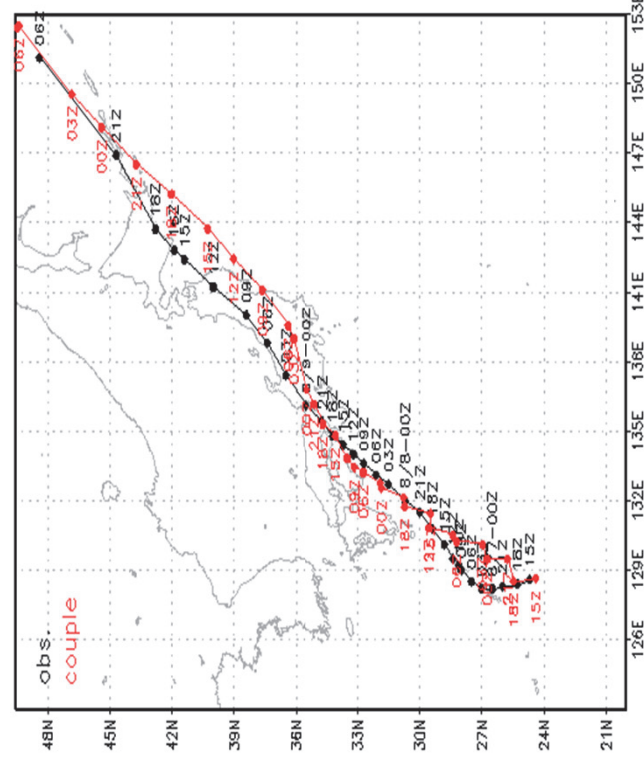


$\Delta h = 50\text{km}$



$\Delta h = 5\text{km}$

Simulation of Typhoon MANGKHUT in 2003 using the Earth Simulator



Simulation of Geologic CO₂ Storage

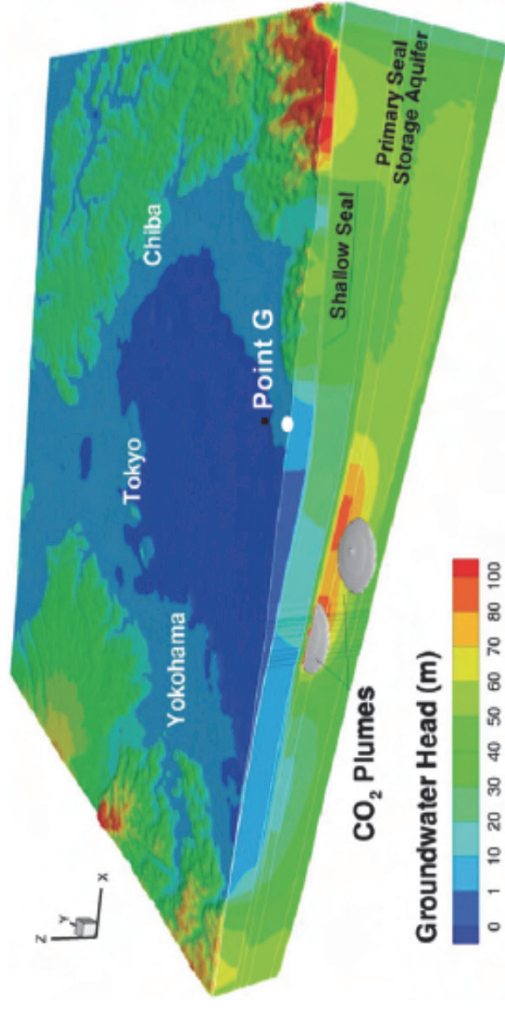
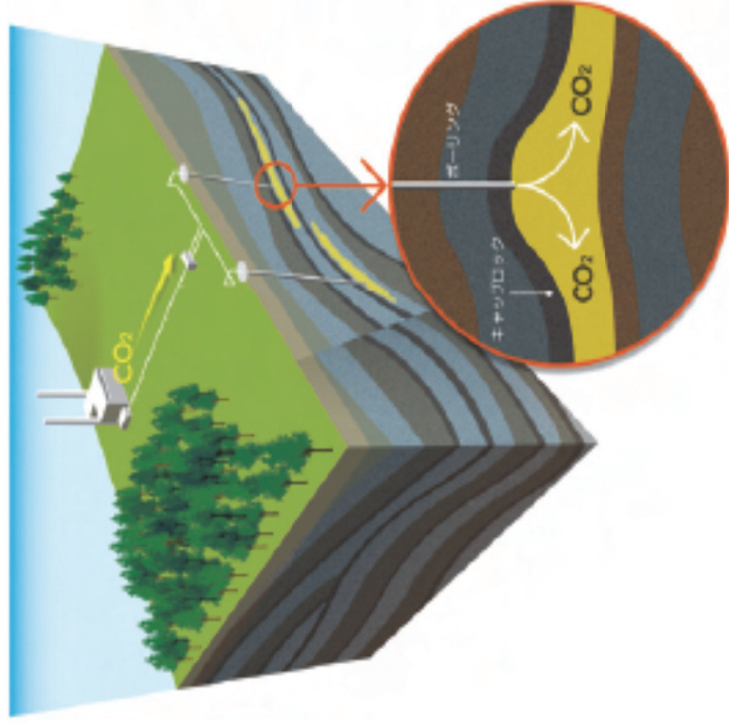
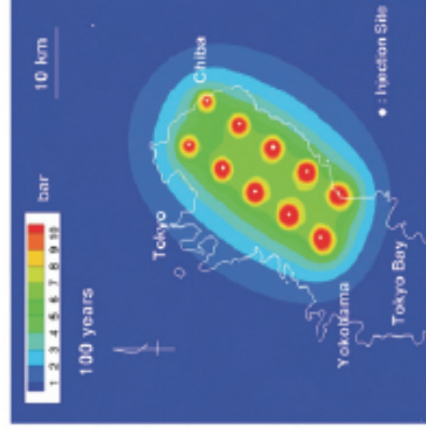
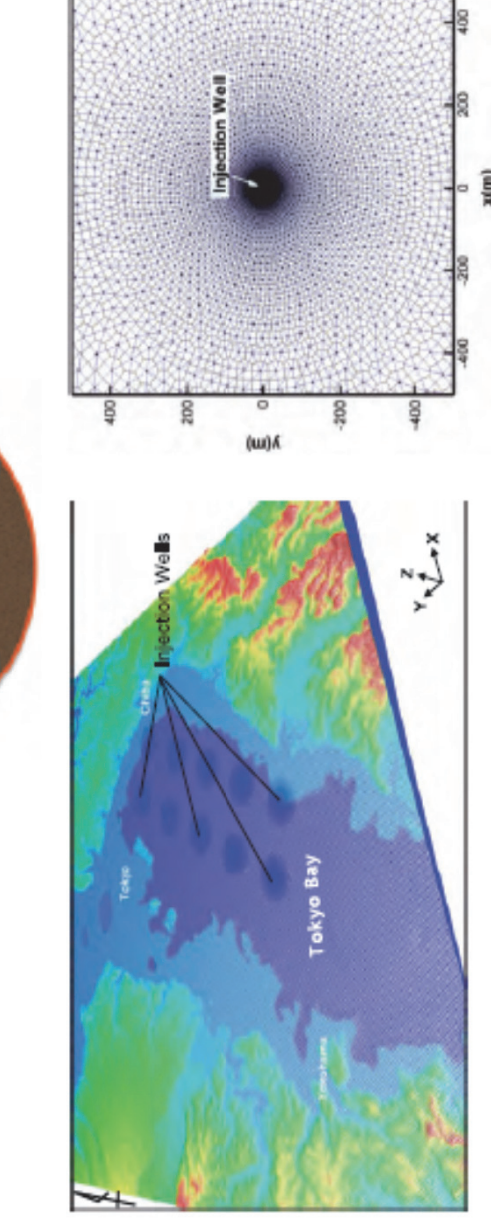
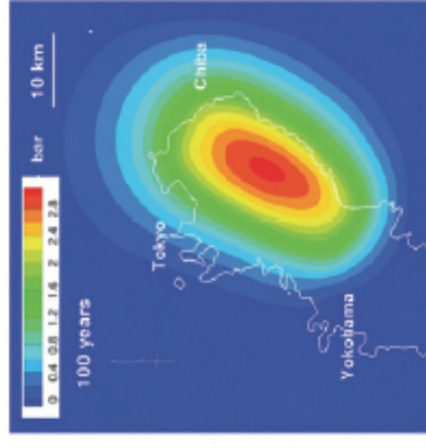


図-4 CO₂ 圧入後の地下水圧 (全水頭換算) の分布 (100 年後)



(a) 深部遮蔽層下面



(b) 浅部遮蔽層下面

図-5 圧力上昇量の平面分布 (初期状態からの増分、圧入開始から 100 年後)

[Dr. Hajime Yamamoto, Taisei]

Simulation of Geologic CO₂ Storage

- International/Interdisciplinary Collaborations
 - Taisei (Science, Modeling)
 - Lawrence Berkeley National Laboratory, USA (Modeling)
 - Information Technology Center, the University of Tokyo (Algorithm, Software)
 - JAMSTEC (Earth Simulator Center) (Software, Hardware)
 - NEC (Software, Hardware)
- 2010 Japan Geotechnical Society (JGS) Award

Science

Modeling

Algorithm

Software

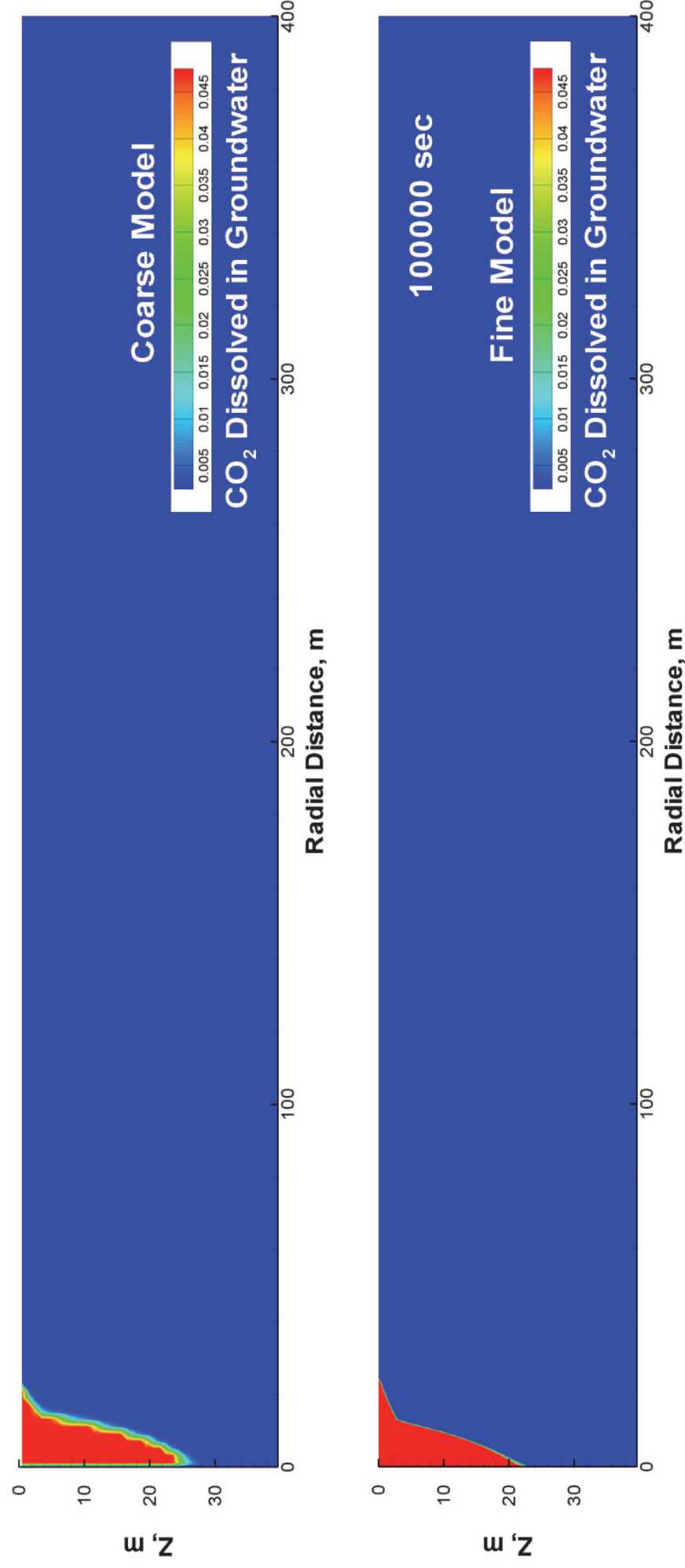
Hardware

Simulation of Geologic CO₂ Storage

- Science
 - Behavior of CO₂ in supercritical state at deep reservoir
- PDE's
 - 3D Multiphase Flow (Liquid/Gas) + 3D Mass Transfer
- Method for Computation
 - TOUGH2 code based on FVM, and developed by Lawrence Berkeley National Laboratory, USA
 - More than 90% of computation time is spent for solving large-scale linear equations with more than 10^7 unknowns
- Numerical Algorithm
 - Fast algorithm for large-scale linear equations developed by Information Technology Center, the University of Tokyo
- Supercomputer
 - Earth Simulator (Peak Performance: 130 TFLOPS)
 - NEC, JAMSEC

Concentration of CO₂ in Groundwater

Mesheres with higher resolution provide more accurate prediction $\Rightarrow$ Larger Model/Linear Equations



Motivation for Parallel Computing, again

- Large-scale parallel computer enables fast computing in large-scale scientific simulations with detailed models. Computational science develops new frontiers of science and engineering.
- Why parallel computing ?
 - faster
 - larger
 - “larger” is more important from the view point of “new frontiers of science & engineering”, but “faster” is also important.
 - + more complicated
 - Ideal: Scalable
 - Solving N^x scale problem using N^x computational resources during same computation time.

- Target: Parallel FEM
- Supercomputers and Computational Science
- **Overview of the Class**
- Future Issues

Prerequisites

- Completed one of the following classes
 - Technical & Scientific Computing I (4820-1027)
 - Seminar on Computer Science I (4810-1204)
- Or, equivalent knowledge and experience in FEM and FEM programming.
 - <http://nkl.cc.u-tokyo.ac.jp/14s/>
- Knowledge and experiences in fundamental methods for numerical analysis (e.g. Gaussian elimination, SOR)
- Knowledge and experiences in UNIX
- Experiences in programming using FORTRAN or C
- Account for Educational Campuswide Computing System (ECC System) should be obtained in advance:
 - <http://www.ecc.u-tokyo.ac.jp/ENGLISH/index-e.html>

Grading by Reports ONLY

- MPI (Collective Communication) (S1)
- MPI (1D Parallel FEM) (S2)
- Parallel FEM (S3)
- Sample solutions will be available
- Deadline: February 14th (Sat) 17:00
 - By E-mail: [nakajima\(at\)cc.u-tokyo.ac.jp](mailto:nakajima(at)cc.u-tokyo.ac.jp)
 - You can bring hard-copy's to my office ...

Homepage

- <http://nkl.cc.u-tokyo.ac.jp/14w/>
 - General information is available
 - Class materials will be uploaded before Friday evening
 - No hardcopy of course materials are provided (Please print them by yourself)

Schedule

Year	Date	Contents
2014	October 06 (M)	(No Class)
	October 15 (W)	Introduction
	October 20 (M)	Data Structure for Parallel FEM
	October 27 (M)	Oakleaf-FX
	November 07 (F)	Parallel Programming by MPI (1)
	November 10 (M)	Parallel Programming by MPI (2)
	November 17 (M)	(No Class)
	December 01 (M)	Introduction to Tuning/Optimizazation
	December 08 (M)	Example for Report #1
	December 15 (M)	Parallel Programming by MPI (3)
	December 22 (M)	Parallel Programming by MPI (4)
2015	January 05 (M)	Example for Report #2
	January 19 (M)	Parallel 3D FEM (1)
	January 26 (M)	Parallel 3D FEM (2)
	February 02 (M)	Parallel 3D FEM (3)

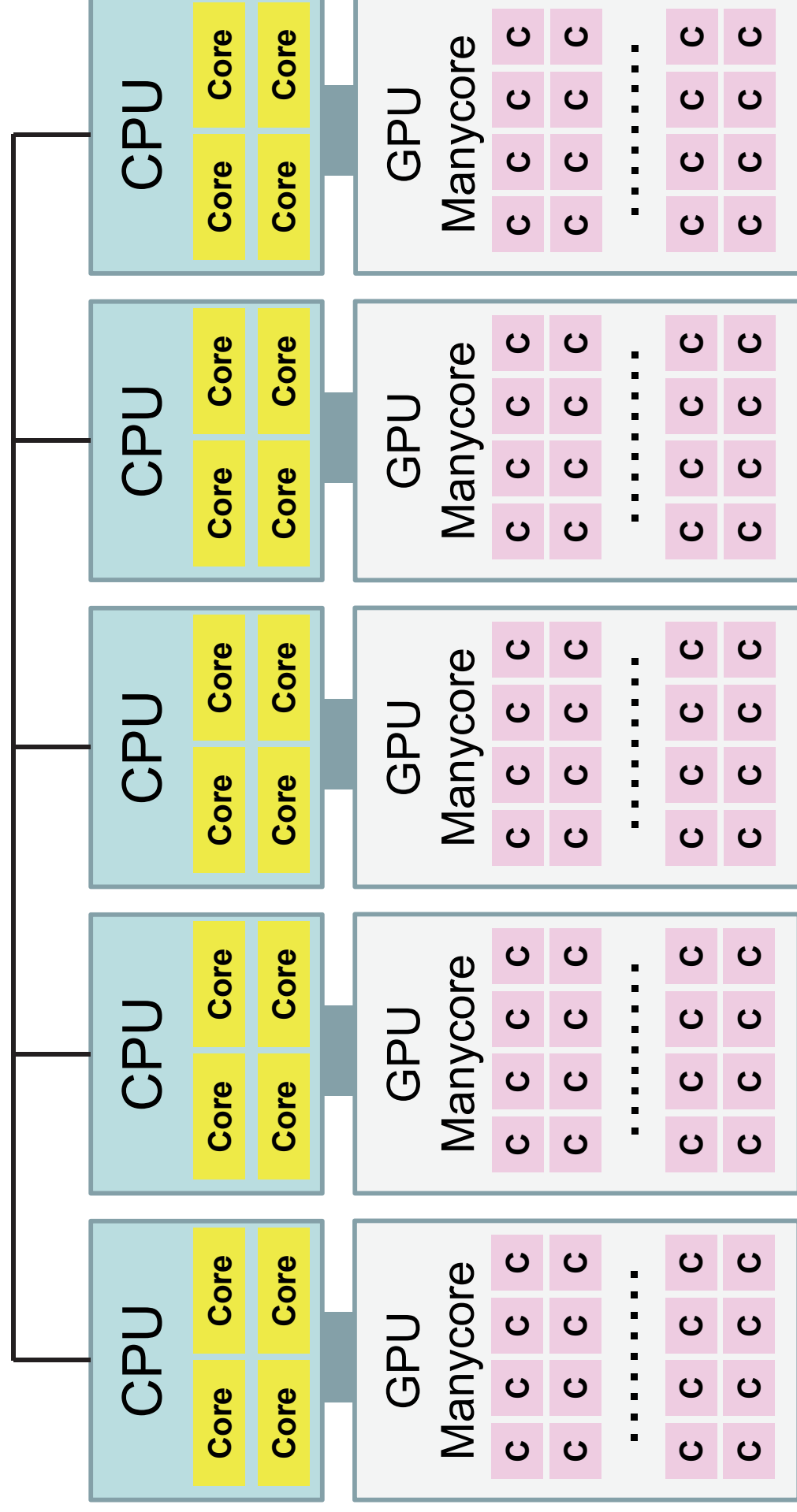
- Target: Parallel FEM
- Supercomputers and Computational Science
- Overview of the Class
- **Future Issues**

Key-Issues towards Appl./Algorithms on Exa-Scale Systems

Jack Dongarra (ORNL/U. Tennessee) at ISC 2013

- Hybrid/Heterogeneous Architecture
 - Multicore + GPU/Manycores (Intel MIC/Xeon Phi)
 - Data Movement, Hierarchy of Memory
- Communication/Synchronization Reducing Algorithms
- Mixed Precision Computation
- Auto-Tuning/Self-Adapting
- Fault Resilient Algorithms
- Reproducibility of Results

Supercomputers with Heterogeneous/Hybrid Nodes



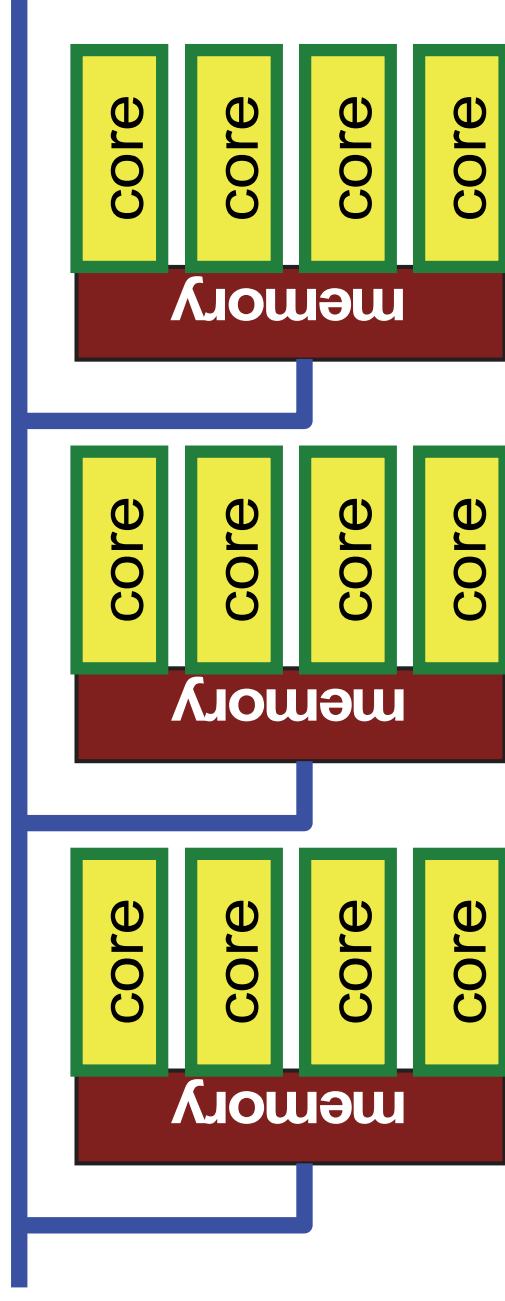
Hybrid Parallel Programming Model is essential for Post-Peta/Exascale

Computing

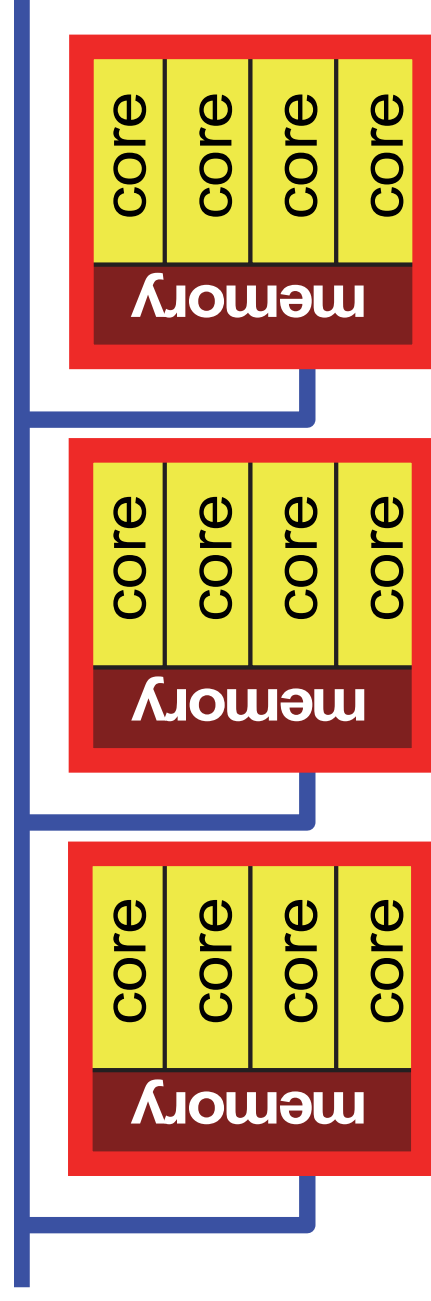
- Message Passing (e.g. MPI) + Multi Threading (e.g. OpenMP, CUDA, OpenCL, OpenACC etc.)
- In K computer and FX10, hybrid parallel programming is recommended
 - MPI + Automatic Parallelization by Fujitsu's Compiler
- Expectations for Hybrid
 - Number of MPI processes (and sub-domains) to be reduced
 - $O(10^8-10^9)$ -way MPI might not scale in Exascale Systems
 - Easily extended to Heterogeneous Architectures
 - CPU+GPU, CPU+Manycores (e.g. Intel MIC/Xeon Phi)
 - MPI+X: OpenMP, OpenACC, CUDA, OpenCL

Flat MPI vs. Hybrid

Flat-MPI: Each PE -> Independent



Hybrid: Hierarchical Structure



In this class...

- You do not have enough time to learn hybrid parallel programming model.
- But you can easily extend the ideas in materials on MPI and (OpenMP) to hybrid parallel programming models.
- Anyway, MPI is essential for large-scale scientific computing. If you want to something new using supercomputers, you must learn MPI, then OpenMP.
 - You don't have to be attracted by PGAS (e.g. HPF), automatic parallelization (自動並列化), etc.

Example of OpenMP/MPI Hybrid

Sending Messages to Neighboring Processes

MPI: Message Passing, OpenMP: Threading with Directives

```
!C
!C- SEND

      do neib= 1, NEIBPETOT
        II= (LEVEL-1)*NEIBPETOT
        istart= STACK_EXPORT(II+neib-1)
        inum = STACK_EXPORT(II+neib ) - istart
!$omp parallel do
      do k= istart+1, istart+inum
        WS(k-NEO)= X(NOD_EXPORT(k))
      enddo

      call MPI_Isend (WS(istart+1-NEO), inum, MPI_DOUBLE_PRECISION, &
& NEIBPE(neib), 0, MPI_COMM_WORLD, &
& req1(neib), ierr)
      enddo
```

Parallel Programming Models

- Multicore Clusters (e.g. K, FX10)
 - MPI + OpenMP and (Fortran/C/C++)
- Multicore + GPU (e.g. Tsubame)
 - GPU needs host CPU
 - MPI and [(Fortran/C/C++) + CUDA, OpenCL]
 - complicated,
 - MPI and [(Fortran/C/C++) with OpenACC]
 - close to MPI + OpenMP and (Fortran/C/C++)
- Multicore + Intel MIC/Xeon-Phi (e.g. Stampede)
 - Xeon-Phi needs host CPU (currently)
 - MPI + OpenMP and (Fortran/C/C++) is possible
 - + Vectorization

Future of Supercomputers (1/2)

- Technical Issues
 - Power Consumption
 - Reliability, Fault Tolerance, Fault Resilience
 - Scalability (Parallel Performance)
- Petascale System
 - 2MW including A/C, 2M\$/year, $O(10^5 \sim 10^6)$ cores
- Exascale System ($10^3 \times$ Petascale)
 - 2018-2020
 - 2GW (2 B\$/year !), $O(10^8 \sim 10^9)$ cores
 - Various types of innovations are on-going
 - to keep power consumption at 20MW (100x efficiency)
 - CPU, Memory, Network ...
 - Reliability

Future of Supercomputers (2/2)

- Not only hardware, but also numerical models and algorithms must be improved:
 - 省電力アルゴリズム (Power-Aware/Reducing)
 - 耐故障アルゴリズム (Fault Resilient)
 - 通信削減アルゴリズム (Communication Avoiding/Reducing)
- Co-Design by experts from various area (SMASH) is important
 - Exascale system will be a special-purpose system, not a general-purpose one.